



Documents



OpenSim Tutorial

October 15, 2011

AACPDM Annual Meeting, Las Vegas, NV

Jennifer Hicks and Ajay Seth

Website: SimTK.org/home/opensim

Acknowledgments

[OpenSim](#) was developed as a part of [SimTK](#) and funded by the [Simbios](#) National Center for Biomedical Computing through the National Institutes of Health and the NIH Roadmap for Medical Research, Grant U54 GM072970. Information on the National Centers can be found at <http://nihroadmap.nih.gov/bioinformatics>. OpenSim is additionally funded by the National Center for Simulation in Rehabilitation Research (NCSRR), a National Center for Medical Rehabilitation Research supported by research infrastructure grant R24 HD065690.

Trademarks and Copyright and Permission Notice

SimTK and Simbios are trademarks of Stanford University. The documentation for OpenSim is freely available and distributable under the MIT License.

Copyright (c) 2009 Stanford University

Permission is hereby granted, free of charge, to any person obtaining a copy of this document (the "Document"), to deal in the Document without restriction, including without limitation the rights to use, copy, modify, merge, publish, distribute, sublicense, and/or sell copies of the Document, and to permit persons to whom the Document is furnished to do so, subject to the following conditions:

This copyright and permission notice shall be included in all copies or substantial portions of the Document.

THE DOCUMENT IS PROVIDED "AS IS", WITHOUT WARRANTY OF ANY KIND, EXPRESS OR IMPLIED, INCLUDING BUT NOT LIMITED TO THE WARRANTIES OF MERCHANTABILITY, FITNESS FOR A PARTICULAR PURPOSE AND NONINFRINGEMENT. IN NO EVENT SHALL THE AUTHORS, CONTRIBUTORS OR COPYRIGHT HOLDERS BE LIABLE FOR ANY CLAIM, DAMAGES OR OTHER LIABILITY, WHETHER IN AN ACTION OF CONTRACT, TORT OR OTHERWISE, ARISING FROM, OUT OF OR IN CONNECTION WITH THE DOCUMENT OR THE USE OR OTHER DEALINGS IN THE DOCUMENT.

Table of Contents

1	TUTORIAL OVERVIEW.....	9
1.1	Introduction to OpenSim	9
1.2	Tutorial Description.....	9
1.3	Audience.....	9
1.4	Learning Objectives.....	9
1.5	Format.....	10
1.6	Where to Find Additional Resources and Support.....	10
1.6.1	The OpenSim GUI.....	10
1.6.2	OpenSim User’s Guide	10
1.6.3	Model and Simulation Repository	11
1.6.4	Additional Online Resources	11
1.6.5	Publications.....	11
1.7	OpenSim GUI Overview.....	12
2	MUSCULOSKELETAL MODEL OF THE LOWER EXTREMITY	13
2.1	Loading a Model	13
2.2	Viewing & Animating a Model	13
2.3	Coordinates.....	14
2.4	Loading a Motion	14
2.5	Motion Slider	15
2.6	Questions.....	15
2.7	Reach Exercises.....	17
3	MUSCLE-TENDON LENGTHS, & MOMENT ARMS	18
3.1	Using the Plotter.....	18
3.2	Questions.....	19

3.3	Reach Exercises	20
4	ASSESSMENT OF HAMSTRINGS LENGTH DURING CROUCH GAIT.....	21
4.1	File Preparation	21
4.2	Questions.....	22
4.3	Reach Exercises	25
5	REFERENCES.....	26

1 Tutorial Overview

1.1 Introduction to OpenSim

Models of the musculoskeletal system enable one to study neuromuscular coordination, analyze athletic performance, and estimate musculoskeletal loads. OpenSim is freely available software that allows users to develop, analyze, and visualize models of the musculoskeletal system, and to generate dynamic simulations of movement. In OpenSim, a musculoskeletal model consists of rigid body segments connected by joints. Muscles span these joints and generate forces and movement [1]. Once a musculoskeletal model is created, OpenSim enables users to study the effects of musculoskeletal geometry, joint kinematics, and muscle-tendon properties on the forces and joint moments that the muscles can produce. With OpenSim, our goal is to provide a framework that allows the biomechanics community to create, share, and extend a library of models and dynamic simulation tools.

1.2 Tutorial Description

Computer simulation has emerged as a powerful method to understand the dynamics of human movement and evaluate gait disorders in children with cerebral palsy. This course will provide a hands-on introduction to computer simulation that is accessible to clinicians of all backgrounds. Participants will learn about the capabilities and limitations of computer simulation and receive hands-on instruction about how to use OpenSim, a freely available software package for simulating movement.

1.3 Audience

Clinicians who want to learn how computer simulation can be used to answer clinical questions about gait. Participants will be asked to bring a laptop computer and will be given instructions on how to download and install OpenSim (a free software package) prior to the course.

1.4 Learning Objectives

A team of computer simulation experts from the National Center for Simulation in Rehabilitation Research (NCSRR) at Stanford University will introduce participants to the basics of computer simulation and its relevance to the treatment of gait pathology. In the hands-on portion of the course, participants will learn how to use the OpenSim software package to estimate hamstrings

lengths. Additional clinical applications of OpenSim will also be described. The specific learning objectives of the course are:

- Describe a musculoskeletal model and its component parts
- Load a model in OpenSim and animate it with gait kinematics
- Plot hamstrings muscle-tendon lengths over the gait cycle
- List the capabilities and limitations of computer simulation

1.5 Format

Each section in this handout guides you through certain tools within OpenSim's GUI and asks you to answer a few questions. The menu titles and option names you must select and any commands you must type to run OpenSim will appear in **bold face**. The questions can be answered based on information from OpenSim and basic knowledge of the human musculoskeletal system. As you complete each section, feel free to explore OpenSim and the lower extremity model further on your own, with the "Reach" questions at the end of the section.

1.6 Where to Find Additional Resources and Support

There are many resources available to help with troubleshooting, access models and simulation data, and interact with the rest of the OpenSim community.

1.6.1 The OpenSim GUI

The OpenSim Help menu provides the following resources:

- Direct links for filing a bug or requesting a new feature.
- Direct links to three tutorials for becoming familiar with the OpenSim GUI.

1.6.2 OpenSim User's Guide

The User's Guide is an extensive resource for most of the features available in OpenSim. For assistance using the GUI and learning about setting up Tools in OpenSim, please refer to the OpenSim User's Guide that is available under "OpenSim Documentation" at https://simtk.org/docman/?group_id=91.

1.6.3 Model and Simulation Repository

You can create your own models of musculoskeletal structures and dynamic simulations of movement in OpenSim, as well as take advantage of computer models and dynamic simulations that other users have developed and shared. For example, you can use existing computer models of the human lower limb, upper limb, cervical spine, and whole body, which have already been developed and posted at <https://simtk.org/home/nmblmodels>. You can also use dynamic simulations of walking and other activities that have been developed, tested, and posted on SimTK.org. We encourage you to share your models and simulations with the research community by setting up a project on SimTK.org.

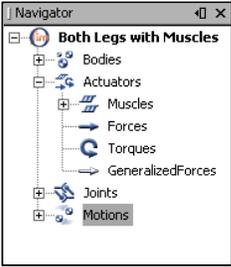
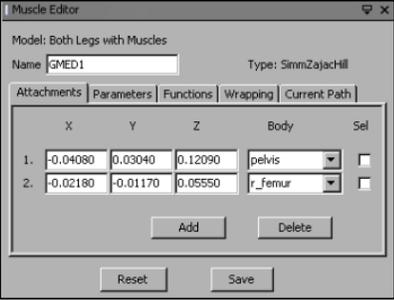
1.6.4 Additional Online Resources

There are many resources available online for support both during and after the workshop. This includes the User's Guide and model repository described above, as well as a user forum, tutorials, examples, webinars, and many other resources. We've recently launched a new website that serves as a portal to these resources. It can be found at <http://opensim.stanford.edu>. You can also find more about OpenSim and related projects by other researchers around that world at the SimTKorg project site at <http://simtk.org/home/opensim>.

1.6.5 Publications

You can find additional information in the following article: Delp, S.L., Anderson, F.C., Arnold, A. S., Loan, P., Habib, A., John, C., Guendelman, E.G., Thelen, D.G., OpenSim: Open-source software to create and analyze dynamic simulations of movement. *IEEE Transactions on Biomedical Engineering*, vol. 54, no. 11, pp. 1940-1950, 2007. Please cite this work in any of your own publications that use OpenSim.

1.7 OpenSim GUI Overview

GUI Components	
Title	Screenshot
Toolbar	
Motion Text Box	
Motion Slider / Video Controls	
View Window	
Navigator Window	
Coordinates Window	
Muscle Editor	

2 Musculoskeletal Model of the Lower Extremity

In this section, you will load a model of the lower extremity [2] into OpenSim and make the model “walk.” The model represents an adult subject with an approximate height of 1.8 m and an approximate mass of 75 kg. The model consists of 13 rigid body segments and includes the lines of action of 86 muscles (43 per leg).

2.1 Loading a Model

The first model you will analyze is entitled *Both Legs with Muscles*. To load this musculoskeletal model into OpenSim:

- Click the **File** menu and select **Open Model**.
- Find the **examples** folder, which is located under your OpenSim installation directory, e.g., *C:\Program Files\OpenSim 1.0*.
*Note: There are several different example models and motions in the **examples** folder. All of the model and motion files used in the remainder of the tutorial will be located in this **examples** folder.*
- Open the **BothLegs** folder, select the file **BothLegs.osim**, and click **Open**.

After loading a model, its name will appear in the model drop down menu, located in the toolbar, and in the Navigator window. To see the Navigator window, which also provides specific information about the bodies, muscles, and joints in the model, click the **Window** menu and select **Navigator**. To expand a Navigator heading, click the plus icon  to its left.

Note: If already opened, you can also view the Navigator window by clicking its title bar.

2.2 Viewing & Animating a Model

OpenSim allows you to orient the model using your mouse.

ROTATE To rotate the view, click and hold the **left mouse button** and drag the mouse.

TRANSLATE To translate the view, click and hold the **center mouse button** and drag the mouse.

ZOOM To zoom, click and hold the **right mouse button**.

To zoom in, drag the mouse down. To zoom out, drag the mouse up.

In addition to your mouse, there are six orienting icons located along the right side of the View window. To view the model in the $-X$ direction, click the  icon. Similarly, click on the other icons to view along the other principal directions. To see the axes of the world reference frame, click the axes icon  located on the right side of the View window.

2.3 Coordinates

The Coordinates window contains sliders that correspond to joint coordinates in the model. To see the Coordinates window, click the **Window** menu and select **Coordinates**. For the current model, the orientation of the pelvis corresponds to the orientation of the model.

Note: If already opened, you can also view the Coordinates window by clicking its title bar.

- The first three sliders correspond to rotations of the pelvis about the Z, X, and Y-axes of the “world” reference frame. To rotate the pelvis about the Z-axis, drag the **rZ slider**. Similarly, to rotate the pelvis about the other two axes, drag the corresponding slider.

Note: These rotations are different than rotating the model view.

- The remaining sliders correspond to joint rotations and control a single degree of freedom. To rotate the joints, drag the sliders or type in a desired joint angle in the adjacent textbox.
- To save a pose, or a specific set of joint coordinates, for later use in the tutorial:
 - Restore the default joint coordinates by clicking the **Poses** button and selecting **Default**.
 - Flex the right hip 45° by typing **45** into the **r_hip_flexion** textbox and pressing **Enter**.
 - Click the **Poses** button, select **New**, type **r hip flex 45** in the textbox, and click **OK**.

2.4 Loading a Motion

To animate the model, you need to load an associated motion file into OpenSim.

- Click the **File** menu and select **Load Motion**. Ensure you are in the **BothLegs** directory, select the file **BothLegsWalk.mot**, and click **Open**. This motion file describes a normal gait.

After loading a motion, its name will appear in the motion textbox, located on the toolbar. Additionally, a new branch will appear in the Navigator titled **Motions**. Expand it to see all motions loaded for a particular model, as shown.



2.5 Motion Slider

The motion slider corresponds to the current motion file. To make the model “walk”, drag the motion slider. To animate the model, use the **video control** buttons, e.g., click **play** ▶. There are also buttons to **loop** ↻, **pause** ||, and control the **speed** of the animation.

2.6 Questions

1. Degrees of Freedom

- a. Use the Coordinate slider to view the degrees of freedom of the model. *How many degrees of freedom does the model have? List them.*

- b. All models are approximations. Compare the degrees of freedom in the model to the degrees of freedom in your lower limbs. *Which motions have been simplified? Which motions have not been modeled at all?*

2. Muscle Paths

- a. Muscle-tendon paths are represented in OpenSim by a series of points connected by line segments. To see a list of all the muscles:
 - In the Navigator, expand the **Actuators**, **Muscles**, and **all** headings.
 - To display a single muscle, **right-click** on a specific muscle name under the **all** group, e.g., *GMED1*, and select **Display > Show Only** from the popup menu.
 - To toggle the display of all muscles, **double-click** on the **Muscles** or **all** heading.

*Note: **Double-clicking** on a body, muscle group, or muscle heading in the Navigator toggles its display.*

In this model, the *gluteus medius* is represented by multiple lines of action (e.g., *GMED1*, *GMED2*, *GMED3*).

Name two other muscles in the model that are represented with multiple lines of action. Why do you think these muscles are represented in this way?

Hint: Other muscles with multiple lines of action use the same naming convention as the *gluteus medius*.

- b.** For some muscles, two points, the muscle origin and insertion, are sufficient to describe the muscle path. For other muscles that wrap over bones or are constrained by retinacula, intermediate *wrapping* or *via* points must be defined. To view these *wrapping* points:
- Zoom in on the right knee joint using the right mouse button.
 - Hide all other muscles except the ***r knee extensors*** muscle group: Double click ***all muscles*** to hide all muscles, then double click on ***r knee extensors*** to only show this muscle group.
 - Fully flex the right knee using the ***r_knee_angle*** Coordinates slider.

Notice that wrapping points are introduced in some of the knee extensors at certain knee angles, such that the muscles appear to wrap around the bones.

Which knee extensor muscles have wrapping points? At what knee angle do they occur?

2.7 Reach Exercises

1. How many muscles are in the model? Is this greater than the number of degrees of freedom? What is the minimum number of muscles required to fully actuate the model?

Hint: Full actuation of the knee, for example, means both knee flexion and knee extension.

2. Modeling Limitations

Some muscles in the lower limb model pass through the bones or deeper muscles at extreme ranges of motion. Zoom in on the right hip, and display only the *GMAX3* muscle (*r hip extensors* group). Examine this muscle for the full range of hip flexion angles.

Do you see any problems with GMAX3? In what ways are point-to-point representations of muscle paths a simplification of musculoskeletal geometry?

3 Muscle-tendon Lengths, & Moment Arms

In this section, you will investigate how muscle-tendon lengths and moment arms depend on limb configuration. Musculoskeletal geometry is very important to the function of muscles and to the development of quantitative musculoskeletal models. Muscle-tendon forces depend upon the muscle-tendon length, and joint moments depend upon both muscle-tendon forces and moment arms. Therefore, accurate specification of musculoskeletal geometry is essential in developing an accurate model for predicting muscle-tendon forces and joint moments.

3.1 Using the Plotter

OpenSim's Plotter allows you to plot muscle-tendon properties, such as length, moment arm, force, and joint moment. To generate a plot of *fiber-length vs. knee angle* for the *rectus femoris* and *vastus intermedius* muscles:

- Return the model to its original pose by clicking **Poses > Default** in the Coordinates window.
Note: Plots are created for the current configuration of the model. Your plots will be made for the default pose.
- To open a new plot, click the **Tools** menu and select **Plot**. In the plotter window, click the **Y-Quantity** button and select **fiber-length**. This variable will appear on the y-axis.
- After selecting an appropriate Y-Quantity, you must select the muscles for which you want to generate curves. Click on the **Muscles** button and a menu will appear.
- To find muscles more quickly, you can filter the muscles by muscle group. Choose the **model** option and use the **group** drop down menu to select **r knee extensors**. The muscles list should now only show the muscles in the right knee extensors group.
- Select *rectus femoris* and *vastus intermedius* from the list by **clicking the checkboxes** labeled **RF** and **VASINT**.

Note: You do not have to close the muscles window as long as the plotter window is open, and your selections are immediately updated in the Muscles textbox. This can be helpful when creating multiple curves on the same plot, which you will do in a few more steps.

- Click **X-Quantity** and select ***r_knee_angle***. This variable will appear on the x-axis.
- To add a title to the plot, click the **Properties** button and type **Fiber-Length vs. Knee Angle** into the textbox under the **Title** tab. Explore the plot properties, and then click **OK**.
- To add the curves to the plot, click **Add**.
Note: The plots use the following SI units: meters (length), Newtons (force), Newton-meters (moment).
- Do *not* close the plot window, as you will be adding more curves in the next section.

3.2 Questions

4. Muscle Fiber Length vs. Joint Angle

- Study the plot of muscle fiber length vs. knee angle. *Do you think these curves would look different if, for example, the right hip was flexed?*

- You will now flex the right hip by recalling the pose you previously saved:

- In the Coordinates window, click **Poses** and select your saved pose (**r hip flex 45**).
- To add curves for 45° hip flexion using the same Quantities and Muscles, click **Add**.

*Note: To print or save a plot, **right-click** on the plot and select **Print** or **Export Image**.*

Compare the two sets of curves you have just plotted. *How have the curves changed? Can you explain your findings? How can bi-articular muscles complicate analysis?*

5. Muscle Moment Arm vs. Joint Angle

Now plot knee extension moment arm vs. knee angle for the same two muscles:

- Return the model to its original position by clicking **Poses > Default**.
- To delete the previous curves, select all the names from the **Curves List** and click **Delete**.
- Click **Y-Quantity**, select **moment arm**, and **r_knee_angle**.
- To add a title to the plot, click the **Properties** button and type **Moment Arm vs. Knee Angle** into the textbox under the **Title** tab.
- To add curves using the same Muscles and X-Quantity as previously selected, click **Add**.

*Note: If you **hover** the cursor over a curve, a tool tip will give the coordinates at that particular point.*

Study the plot of knee extension moment arm vs. knee angle for rectus femoris and vastus intermedius. *At what knee angles do the moment arms peak? What are the peak moment arms?*

You may notice that the moment arm curves have a discontinuity. *At what knee angle does the discontinuity occur? What do you think causes this? Hint: Look at Question 2.b*

3.3 Reach Exercises

Feel free to make more plots for other limb positions, muscles, and/or joints. When you are ready to continue with the tutorial, close the plotter window and close the *Both Legs with Muscles* model by clicking the **File** menu and selecting **Close Model**. Do not save the model settings to file.

4 Assessment of Hamstrings Length During Crouch Gait

In this final section of the tutorial, you will use OpenSim to investigate a possible cause of crouch gait, one of the most common walking abnormalities among individuals with cerebral palsy. It is characterized by excessive flexion of the knee during stance phase, which is often accompanied by exaggerated flexion and internal rotation of the hip. One hypothesized cause of crouch gait is short hamstrings, and orthopaedic surgeons will sometimes lengthen the hamstrings of such patients in an attempt to improve their posture and gait. However, other causes of excessive knee flexion are possible (e.g. weak ankle plantarflexors), and lengthening the hamstrings can compromise the strength of these muscles [3]. How can a surgeon determine whether a hamstring lengthening procedure is warranted?

One possible way to judge whether a patient's hamstrings are shorter than "normal" is to develop a musculoskeletal model and compare the length of the hamstrings during the patient's crouch gait cycle to the length of the hamstrings during a normal gait cycle. Suppose that an orthopaedic surgeon has brought you some kinematic data for a patient who walks with a crouch gait. The surgeon is contemplating whether to operate, and wants your opinion.

4.1 File Preparation

Follow these steps to load the crouch gait and normal gait files:

- Load the model file ***SeparateLegs.osim*** entitled *Separate Legs with Muscles*. This model is located in the directory ***examples/SeparateLegs***. *Separate Legs with Muscles* is similar to *Both Legs with Muscles*, except that it has separate left and right pelvis segments that connect to the sacrum.

Note: All of the tutorial models and motions are relative to your OpenSim installation directory, e.g., C:\Program Files\OpenSim 1.0.

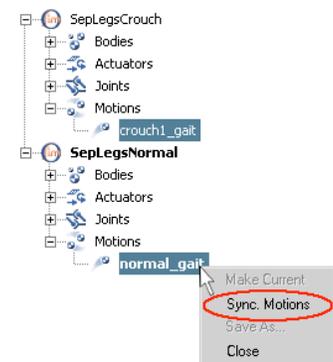
- To rename a loaded model, **right-click** on the model name in the Navigator and select **Rename** from the popup menu. Type ***SepLegsCrouch*** into the textbox and click **OK**.

Note: Renaming in this way does not affect the actual file name of the model.

- Load the motion file ***crouch1.mot***, which is in the same folder as *seplegs* model. This motion contains crouch gait data.
- OpenSim has the ability to load multiple models simultaneously. To open a second model, load the ***SeparateLegs.osim*** file again.
*Note: If you do not see both models after loading, press the **r** key.*
- To rename the second model, **right-click** on the current model name and select **Rename**. Type ***SepLegsNormal*** into the textbox and click **OK**.
*Note: Throughout the rest of the tutorial, these two models will be referred to as **crouch** and **normal**.*
- You can adjust the position of the model in the viewer. **Right-click** on the ***SepLegsNormal*** model in the **Navigator** window and select **Display > Model Offset**. Set the **X** offset to 1 and click **OK**.

The second model you loaded automatically becomes the *current* model. Notice that the *non-current* model becomes translucent. Any action, such as loading a motion, will be applied only to the current model.

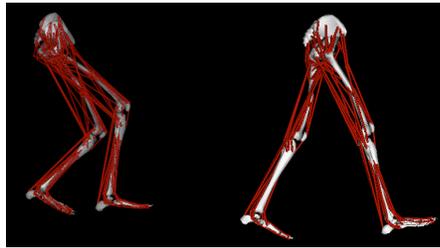
- Making sure that the *normal* model is still current, load the second motion file ***normal.mot***. This motion file contains normal gait data.
- OpenSim can synchronize multiple motions, allowing you to animate multiple models simultaneously. To do this, expand the **Motions** branch of each model in the Navigator, hold down **ctrl**, and select both motions names such that each name is highlighted. **Right-click** on either motion name, then select **Sync. Motions** from the popup menu, as shown.



4.2 Questions

6. Range of Motion

To animate the models and visually compare the crouch gait data to the normal gait data, click **play**. Notice that both motions are synchronized, as shown. Be sure to loop the animation, adjust the play speed, and rotate the models. *What differences do you observe?*



Now quantitatively compare knee flexion angles over the crouch and normal gait cycles.

- In a new plot, edit the text in the **Curve Name** textbox to read **Normal Gait**.
- Click **Y-Quantity**, select **normal_gait**, and select **r_knee_angle**. Click **OK**.
- Click **X-Quantity** and select **normal_gait**. Click **OK**.
- To add the curve of *right knee angle vs. gait cycle*, click **Add**.
- Make the *crouch* model current by **right-clicking** on the **SepLegsCrouch** model in the **Navigator** window and selecting **Make Current**.
- In the **Curve Name** textbox edit the text to read **Crouch Gait**, then click **Add**.
- In the same plotter window, click **Y-Quantity**, select **crouch1_gait**, and select **r_knee_angle**. Click **OK**.
- Click **X-Quantity** and select **crouch1_gait**. Click **OK**.

Can you identify the intervals at which heel strike, stance, toe off, and swing phase occur for a “normal” gait cycle? Sketch a plot of the curve, and label the intervals.

What is the “normal” range of knee flexion during stance phase? How does this knee flexion curve for crouch gait compare to the normal gait data?

7. Hamstrings Length

To address the surgeon's question, compare the hamstrings length over the crouch gait cycle to the hamstrings length over the "normal" gait cycle.

- To delete the previous curves, select all the names from the **Curves List** and click **Delete**.
*Note: To select multiple curve names, hold down **ctrl** while selecting.*
- Make the *normal* model current by selecting it through the **Navigator** pane.
- In the **Curve Name** textbox edit the text to read **Normal Gait**.
- Click **Y-Quantity** and select **muscle-tendon length**.
- Click on **Muscles** and select **Hamstrings** from the list. Click **Close**.
*Note: To quickly find the Hamstrings, type **ham** into the **pattern** textbox.*
- Click **X-Quantity** and select **normal_gait**.
- To add the curve of *hamstrings length vs. gait cycle*, click **Add**.
- To make a similar curve for the crouch gait data, make the *crouch* model current. In the **Curve Name** textbox, edit the name to read **Crouch Gait** Then, click on **Y-Quantity** and re-select **muscle-tendon length**.
- Click on **Muscles** and select **Hamstrings**.
- Click **X-Quantity** and select **crouch1_gait** and then click **Add**.

Study the curves. *Based on the plot, what recommendation would you give the surgeon? Can you think of any limitations of your analysis?*

4.3 Reach Exercises

The orthopaedic surgeon cares for three other patients who walk with a crouch gait. Repeat the above analysis for motion files *crouch2.mot*, *crouch3.mot*, and *crouch4.mot*. Note that you can associate more than one motion with a model. *Would your recommendations to the surgeon be any different for these patients?* If you would like to learn more about this type of analysis, please read reference [3].

5 References

1. Delp, S.L., Anderson, F.C., Arnold, A.S., Loan, P., Habib, A., John, C.T., Guendelman, E., Thelen, D.G. OpenSim: Open-source software to create and analyze dynamic simulations of movement. *IEEE Transactions on Biomedical Engineering*, vol. 55, pp. 1940-1950, 2007.
2. Delp, S.L., Loan, J.P., Hoy, M.G., Zajac, F.E., Topp E.L., Rosen, J.M. An interactive graphics-based model of the lower extremity to study orthopaedic surgical procedures. *IEEE Transactions on Biomedical Engineering*, vol. 37, pp. 757-767, 1990.
3. Arnold, A.S., Liu, M., Ounpuu, S., Swartz, M., Delp, S.L., The role of estimating hamstrings lengths and velocities in planning treatments for crouch gait, *Gait and Posture*, vol. 23, pp. 273-281, 2006.